

$$\text{so, } \vec{a}_{\text{inst}} = \frac{v}{R} \lim_{\Delta t \rightarrow 0} \frac{s}{\Delta t}$$

$$\text{and } s = v \Delta t$$

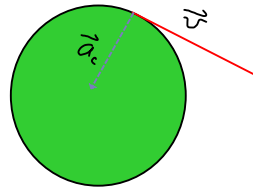
$$\text{so } \vec{a}_{\text{inst}} = \frac{v}{R} \lim_{\Delta t \rightarrow 0} \frac{v \Delta t}{\Delta t}$$

$$= \frac{v}{R} (v)$$

$$\text{so } a_c = \frac{v^2}{R} \quad \begin{array}{l} \text{constant speed} \\ \text{radius of turn} \end{array}$$

centripetal
acceleration

(always towards to
centre of the circular
path)



$$\text{Now } \Delta d = 2\pi r, \quad (\text{for circle})$$

$$\text{so } a_c = \frac{v^2}{r} = \frac{\left(\frac{\Delta d}{\Delta t}\right)^2}{r}$$

$$= \frac{\left(\frac{2\pi r}{\Delta t}\right)^2}{r}$$

$$= \frac{\left(\frac{4\pi^2 r^2}{\Delta t^2}\right)}{r}$$

$$a_c = \frac{4\pi^2 r}{T^2} \quad \text{period}$$

$$\text{or } a_c = 4\pi^2 r f^2 \quad \text{frequency}$$

p. 122 #1, 2

p. 123 #3

p. 126 #6-10, p. 127 #5-7